

Let  $F(a, b, c; z)$  be the Gauss hypergeometric function

$$F(a, b, c; x) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{(1)_n (c)_n} x^n,$$

$$(a)_n = a(a+1)\cdots(a+n-1).$$

Everybody knows some **hypergeometric functions** very well:

**Example:**

$$\arcsin x = xF(1/2, 1/2, 3/2; x^2)$$

**Example:**

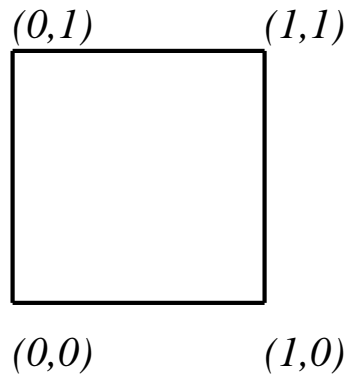
$$-\frac{x_2}{2x_1} \pm \left( \frac{x_2}{2x_1} - \sum_{m=0}^{\infty} \frac{1}{m+1} \binom{2m}{m} \frac{x_1^m x_3^{m+1}}{x_2^{2m+1}} \right) = \frac{-x_2 \pm \sqrt{x_2^2 - 4x_1x_3}}{2x_1}.$$

This is the familiar *quadratic formula* for expressing the two zeros of a quadratic polynomial  $p(z) = x_1z^2 + x_2z + x_3$  in terms of its three coefficients. The quadratic formula satisfies the **GKZ hypergeometric system**

$$(\partial_1\partial_3 - \partial_2^2)f = 0, (x_1\partial_1 + x_2\partial_2 + x_3\partial_3)f = 0, (x_2\partial_2 + 2x_3\partial_3 - 1)f = 0.$$

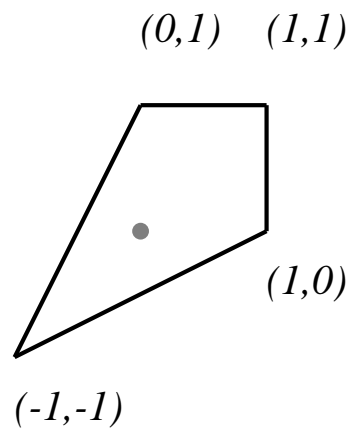
Example:

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$



Example:

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & -1 & 0 \end{pmatrix}$$



**Example:** (Left ideal and system of linear differential equations)

$$n = 1, \text{rank}(R \cdot \{x^2 \partial_x^2 - 1/2\}) = 2.$$

The ideal is the differential equation

$$x^2 \frac{\partial^2 F}{\partial x^2} - \frac{1}{2} F = 0.$$

**Example:**

$$n = 2, \text{rank}(R \cdot \{\partial_x - 1, \partial_y^2 + 1\}) = 2.$$

The ideal is the system of differential equations

$$\frac{\partial F}{\partial x} - F = 0, \frac{\partial^2 F}{\partial y^2} + F = 0.$$

Summary of notions and theorems.

**Example:** 7 solutions attached to each Gröbner fan. The domain of convergence is the corresponding secondary cone.

$H_A(\beta)$  for

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & -1 & 0 \end{pmatrix}, \quad \beta = \left( -\frac{1}{2} \quad \frac{1}{3} \quad -\frac{1}{5} \right)$$

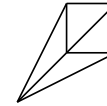
is generated by

$$-\partial_2\partial_5 + \partial_1\partial_3, \quad \partial_5^2 - \partial_2\partial_4$$

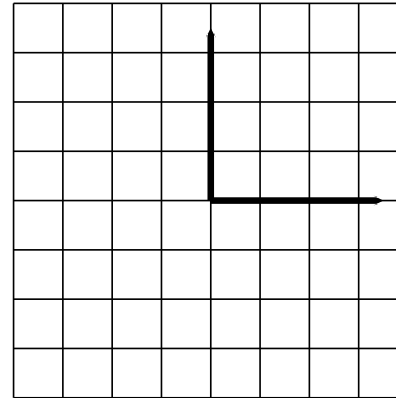
$$x_1\partial_1 + x_2\partial_2 + x_3\partial_3 + x_4\partial_4 + x_5\partial_5 + 1/2, \quad x_1\partial_1 + x_2\partial_2 - x_4\partial_4 - 1/3,$$

$$x_1\partial_1 + x_2\partial_2 + x_3\partial_3 - x_4\partial_4 - 1/5$$

(We will denote by  $A\theta - \beta$  the last 3 equations. Put  $\theta = {}^t(x_1\partial_1, \dots, x_5\partial_5)$ .)

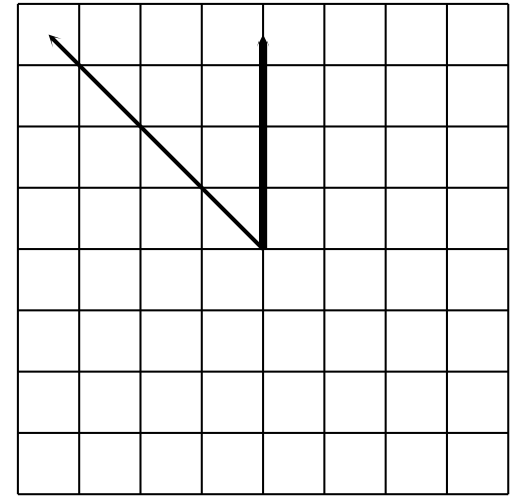
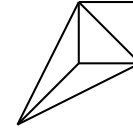


$$\begin{pmatrix} x_5^{-\frac{7}{10}} x_3^{-\frac{2}{15}} x_2^{\frac{1}{3}} \\ x_5^{-\frac{1}{30}} x_4^{-\frac{1}{3}} x_3^{-\frac{2}{15}} \\ x_5^{-\frac{5}{6}} x_2^{\frac{1}{5}} x_1^{\frac{2}{15}} \\ x_5^{-\frac{13}{30}} x_4^{-\frac{1}{5}} x_1^{\frac{2}{15}} \end{pmatrix} \left( 1 + O\left(\frac{x_1 x_3}{x_2 x_5}, \frac{x_2 x_4}{x_5^2}\right) \right)$$



$$\text{in}_{(-w,w)}(H_A(\beta)) = D \cdot \{A\theta - \beta, \theta_1\theta_3, \theta_2\theta_4\}$$

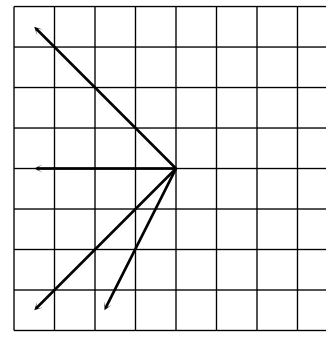
where  $\theta_i = x_i \partial_i$ .



$$\begin{pmatrix} x_3^{-\frac{5}{6}} x_2^{\frac{31}{30}} x_1^{-\frac{7}{10}} \\ x_5^{-\frac{13}{30}} x_4^{-\frac{1}{5}} x_1^{\frac{2}{15}} \\ x_5^{-\frac{1}{30}} x_4^{-\frac{1}{3}} x_3^{-\frac{2}{15}} \\ x_5^{-\frac{31}{30}} x_3^{\frac{1}{5}} x_1^{\frac{1}{3}} \end{pmatrix} \left( 1 + O \left( \frac{x_2 x_5}{x_1 x_3}, \frac{x_2 x_4}{x_5^2}, \frac{x_1 x_3 x_4}{x_5^3} \right) \right)$$

$$\text{in}_{(-w,w)}(H_A(\beta)) = D \cdot \{A\theta - \beta, \theta_2\theta_5, \theta_2\theta_4, \theta_1\theta_3\theta_4\}$$

where  $\theta_i = x_i \partial_i$ .

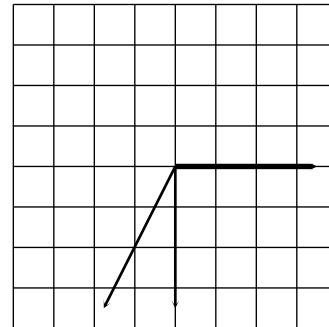


$$\begin{pmatrix}
 x_3^{-\frac{5}{6}} x_2^{\frac{31}{30}} x_1^{-\frac{7}{10}} \\
 -\frac{31}{90} x_3^{-\frac{13}{90}} x_1^{-\frac{1}{90}} \\
 x_4^{-\frac{91}{90}} x_3^{-\frac{73}{90}} x_1^{-\frac{61}{90}} x_5^2 \\
 -\frac{61}{90} x_3^{-\frac{43}{90}} x_1^{-\frac{31}{90}} x_5 \\
 x_4^{-\frac{1}{90}} x_3^{-\frac{73}{90}} x_1^{-\frac{61}{90}} x_5 \\
 x_4^{-\frac{31}{90}} x_3^{-\frac{13}{90}} x_1^{-\frac{1}{90}} \\
 x_3^{-\frac{5}{6}} x_2^{\frac{31}{30}} x_1^{-\frac{7}{10}} \\
 -\frac{61}{90} x_3^{-\frac{43}{90}} x_1^{-\frac{31}{90}} x_5 \\
 x_4^{-\frac{31}{90}} x_3^{-\frac{13}{90}} x_1^{-\frac{1}{90}} \\
 x_4^{\frac{29}{90}} x_3^{-\frac{133}{90}} x_1^{-\frac{121}{90}} x_2^2 \\
 -\frac{5}{6} x_3^{-\frac{31}{30}} x_1^{-\frac{7}{10}} \\
 x_3^{-\frac{1}{90}} x_3^{-\frac{73}{90}} x_1^{-\frac{61}{90}} x_2
 \end{pmatrix}
 \begin{pmatrix}
 1 + O\left(\frac{x_2 x_5}{x_1 x_3}, \frac{x_2 x_4}{x_5^2}, \frac{x_5^3}{x_1 x_3 x_4}\right) \\
 \\
 \\
 \\
 1 + O\left(\frac{x_2 x_5}{x_1 x_3}, \frac{x_5^2}{x_2 x_4}, \frac{x_2^2 x_4}{x_1 x_3 x_5}\right) \\
 \\
 \\
 1 + O\left(\frac{x_2 x_5}{x_1 x_3}, \frac{x_5^2}{x_2 x_4}, \frac{x_1 x_3 x_5}{x_2^2 x_4}, \frac{x_2^3 x_4}{x_1^2 x_3^2}\right)
 \end{pmatrix}$$



$$\begin{pmatrix} x_4^{-\frac{11}{12}} x_2^{-\frac{103}{60}} x_1^{\frac{17}{15}} x_3 \\ x_4^{-\frac{7}{20}} x_2^{-\frac{1}{60}} x_3^{-\frac{2}{15}} \\ x_4^{-\frac{17}{20}} x_3^{\frac{13}{15}} x_2^{-\frac{91}{60}} x_1 \\ x_4^{-\frac{5}{12}} x_2^{-\frac{13}{60}} x_1^{\frac{2}{15}} \end{pmatrix} \left( 1 + O \left( \frac{x_2 x_5}{x_1 x_3}, \frac{x_5^2}{x_2 x_4}, \frac{x_1 x_3 x_5}{x_2^2 x_4}, \frac{x_1^2 x_3^2}{x_2^3 x_4} \right) \right)$$

$$\begin{pmatrix} x_2^{-\frac{43}{60}} x_4^{-\frac{11}{12}} x_1^{\frac{2}{15}} x_5 \\ x_2^{-\frac{31}{60}} x_4^{-\frac{17}{20}} x_3^{-\frac{2}{15}} x_5 \\ x_4^{-\frac{5}{12}} x_2^{-\frac{13}{60}} x_1^{\frac{2}{15}} \\ x_4^{-\frac{7}{20}} x_2^{-\frac{1}{60}} x_3^{-\frac{2}{15}} \end{pmatrix} \left( 1 + O \left( \frac{x_1 x_3}{x_2 x_5}, \frac{x_5^2}{x_2 x_4} \right) \right)$$



- Consider  $n$  points

$$\begin{pmatrix} a_1 \\ w_1 \end{pmatrix}, \dots, \begin{pmatrix} a_n \\ w_n \end{pmatrix}$$

in  $\mathbf{R}^{d+1}$ . Consider the projection

$$p : \begin{pmatrix} y_1 \\ y_2 \\ \cdot \\ \cdot \\ \cdot \\ y_n \\ y_{n+1} \end{pmatrix} \mapsto \begin{pmatrix} y_1 \\ y_2 \\ \cdot \\ \cdot \\ \cdot \\ y_n \end{pmatrix} .$$

Projecting down the lower convex hull of the  $n$  points by the projection  $p$ , we obtain a triangulation of  $A$ .

Let  $\Delta_p$  be the set of points

$$e_0 = 0, e_1, \dots, e_p \in \mathbf{Z}^p.$$

We denote by  $\Delta_p \times \Delta_q$  the set of points  $e_i \times e_j$  put on the hyperplane  $x_1 = 1$ .

Example:

$$\Delta_1 \times \Delta_2 = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{pmatrix}$$