

An Abstract Doubly Nonlinear Volterra Integral Equation

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1. Introduction

This paper is concerned with the existence of solutions to the Volterra integral equation

$$(1.1) \quad u(t) + \int_0^t a(t-s)A(s)(Bu(s)) ds \ni f(t), \quad 0 \leq t \leq T,$$

in a real Hilbert space H . Here $a: [0, T] \rightarrow \mathbf{R}$ is a given kernel, $A(t)$ ($t \in [0, T]$) and B denote nonlinear maximal monotone (possibly multivalued) operators in H , f maps $[0, T]$ into H , and the integral is taken in the sense of Bochner.

In the special case $B = I$ (identity), the existence, uniqueness and asymptotic behavior (as $T \rightarrow \infty$) of solutions of (1.1) was discussed by the author [1–3]. Little is known, however, on the solvability of general nonlinear equations of the form (1.1). Let us remark that by letting $v(t) \in Bu(t)$, equation (1.1) formally reduces to

$$(1.2) \quad B_1 v(t) + \int_0^t a(t-s)A(s)v(s) ds \ni f(t), \quad 0 \leq t \leq T,$$

where $B_1 = B^{-1}$. Equation (1.2) has been studied by Barbu [6, 7] under the assumption that $A(\cdot)$ is independent of t , and recently by Hokkanen [17], who allows both A and B_1 to vary with t . As regards [17], we point out that the domain of $A(t)$ is required to be constant (for all t), and that a technical condition (that also appears in [6, 7]) relating $A(t)$ and B_1 is used. (In particular, if $A(t)$ and B_1 are linear, that condition is close to the monotonicity of the composite mapping $A(t) \circ B_1^{-1}$, $\forall t$.) Unlike [17], in the current paper we allow the domain of $A(t)$ to depend on t . No condition relating $A(t)$ and B is imposed. In addition, our approach is different from the one in [17] (or [6, 7]), in the sense that a distinct approximation procedure is employed.

It is also worth mentioning that in the case when $a = 1$, (1.1) is formally equivalent to a Cauchy problem for a doubly nonlinear evolution equation of the type

$$(1.3) \quad u'(t) + A(t)(Bu(t)) \ni f_1(t), \quad 0 < t < T,$$

where $f_1 : [0, T] \rightarrow H$. This equation has recently been considered by Kenmochi [19] and Kenmochi and Pawlow [20]. It is easy to see that (1.3) can be rewritten as

$$(1.4) \quad \frac{d}{dt} B_1 v(t) + A(t)v(t) \ni f_1(t), \quad 0 < t < T,$$

where $B_1 = B^{-1}$, $v(t) \in Bu(t)$. Equation (1.4) arises as a model for a variety of nonlinear diffusion problems (including free-boundary problems), and has attracted a lot of attention. (See, e.g., [4, 5, 8, 9, 11, 14, 16, 18, 21, 22].)

From an abstract viewpoint, the present study is a direct attempt to generalize to (1.1) the existence theory of Kenmochi and Pawlow [20]. Our approach combines some of the techniques for evolution equations with methods specific to the theory of abstract Volterra equations developed in recent years (cf. e.g., [12, 13].)

The plan of the paper is as follows. In section 2 we recall for easy reference some basic facts about maximal monotone operators and time-dependent subdifferentials. The main existence result is stated and proved in Sections 3 and 4, respectively. A uniqueness theorem is also included. Finally, Section 5 discusses a model problem of physical interest, to which our abstract theory can be applied.

2. Preliminaries

For further background and details of this section we refer the reader to [10, 19, 20]. Throughout this paper H denotes a real Hilbert space with scalar product (\cdot, \cdot) and norm $|\cdot|$. \mathcal{H} will stand for the space $L^2(0, T; H)$ endowed with its usual inner product $\langle \cdot, \cdot \rangle$ and norm $|\cdot|$. We will use the symbols “ \rightarrow ” and “ \rightharpoonup ” to indicate the strong, and respectively, weak convergence in H or \mathcal{H} . Let A be a set-valued operator in H with domain $D(A)$ and range $R(A)$. We say that A is monotone if $(y_2 - y_1, x_2 - x_1) \geq 0$, for all $y_i \in Ax_i$, $i = 1, 2$. A is called maximal monotone if it is monotone, and $R(I + \lambda A) = H$, $\forall \lambda > 0$, where I stands for the identity on H . For a maximal monotone A , one can define the resolvent $J_\lambda = J_\lambda^A = (I + \lambda A)^{-1}$, and the Yosida approximation $A_\lambda = \lambda^{-1}(I - J_\lambda)$, $\forall \lambda > 0$. Several properties of A , J_λ , and A_λ are presented next.

Proposition 2.1. *Let A be maximal monotone in H . Then:*

- (i) A is demiclosed, i.e., the graph of A is closed in $H \times H_w$, where H_w denotes H equipped with the weak topology.
- (ii) J_λ is nonexpansive on H , while A_λ is maximal monotone and Lipschitz continuous on H with λ^{-1} as Lipschitz constant. Moreover $A_\lambda x \in AJ_\lambda x$, $\forall x \in H$.
- (iii) If $x_\lambda \rightarrow x$ and $A_\lambda x_\lambda \rightarrow y$ as $\lambda \rightarrow 0^+$, then $x \in D(A)$ and $y \in Ax$.
- (iv) The operator \mathcal{A} defined in \mathcal{H} by $(\mathcal{A}v)(t) = Av(t)$, a.e. on $(0, T)$, $\forall v \in \mathcal{H}$ is maximal monotone, and $(\mathcal{A}_\lambda v)(t) = A_\lambda v(t)$, a.e. $t \in (0, T)$, $\forall \lambda > 0$, $\forall v \in \mathcal{H}$. (\mathcal{A} is said to be the \mathcal{H} -extension of A .)

An important subclass of maximal monotone operators is that of subdifferentials. Let $\psi : H \rightarrow]-\infty, +\infty]$ be a proper convex, lower semicontinuous (l.s.c.) function, with effective domain $D(\psi) = \{x \in H : \psi(x) < +\infty\}$. Its subdifferential $\partial\psi$ is defined by:

$$\partial\psi(x) = \{y \in H : \psi(z) - \psi(x) \geq (y, z - x) \quad \forall z \in D(\psi)\}.$$

Proposition 2.2. *Let $A = \partial\psi$, where $\psi : H \rightarrow]-\infty, +\infty]$ is proper, convex and l.s.c. Then A is maximal monotone in H , with $A_\lambda = \partial\psi_\lambda$ ($\lambda > 0$), where*

$$\psi_\lambda(x) = \inf_{y \in H} \{\psi(y) + |y - x|^2 / (2\lambda)\}, \quad x \in H.$$

In addition, the following properties hold:

- (i) $\psi_\lambda(z) = \psi(J_\lambda z) + |z - J_\lambda z|^2 / (2\lambda), \quad \forall z \in H, \lambda > 0,$

and

$$\psi_\lambda(z) \uparrow \psi(z) \quad \text{as } \lambda \downarrow 0.$$

- (ii) *If $\lambda_n \downarrow 0$, and $z_n \rightarrow z$ in H (as $n \rightarrow \infty$), then*

$$\psi(z) \leq \liminf \psi_{\lambda_n}(z_n).$$

If also $\{\partial\psi_{\lambda_n}(z_n)\}$ is bounded in H , then

$$\psi_{\lambda_n}(z_n) \longrightarrow \psi(z).$$

- (iii) *If $v \in W^{1,2}(0, T; H)$ and $g \in L^2(0, T; H)$ satisfy $v(t) \in D(A)$, $g(t) \in Av(t)$, a.e. on $(0, T)$, then $t \rightarrow \psi(v(t))$ is absolutely continuous on $[0, T]$ and $(d/dt)\psi(v(t)) = (v'(t), g(t))$, for a.a. $t \in (0, T)$.*

We now consider a family $\{\varphi^t; 0 \leq t \leq T\}$ of proper, convex, l.s.c. functions from H into $[0, +\infty]$ satisfying:

- (φ_1) There exist constants $c_1 > 0$, $\bar{c}_1 \geq 0$ such that

$$\varphi^t(z) \geq c_1|z|^2 - \bar{c}_1, \quad \forall z \in H, \quad \forall t \in [0, T].$$

(φ_2) There exist functions $\alpha \in W^{1,2}(0, T)$ and $\beta \in W^{1,1}(0, T)$ such that for all $s, t \in [0, T]$, $s \leq t$, and $z \in D(\varphi^s)$, there is $\bar{z} \in D(\varphi^t)$ satisfying:

$$\begin{aligned} |\bar{z} - z| &\leq |\alpha(t) - \alpha(s)|(1 + (\varphi^s(z))^{1/2}) \\ \varphi^t(\bar{z}) - \varphi^s(z) &\leq |\beta(t) - \beta(s)|(1 + \varphi^s(z)). \end{aligned}$$

The following is a direct consequence of [19, Lemmas 1.2.1, 1.2.2, 1.5.2, 1.5.3] and [20, Lemmas 2.2, 2.3].

Proposition 2.3. *Let conditions (φ_1), (φ_2) be satisfied. Then*

- (i) *The function $t \rightarrow \partial\varphi_\lambda^t(v(t))$ is measurable for each $\lambda \in (0, 1]$ and $v \in L^1(0, T; H)$.*
- (ii) *There is a constant $c'_1 \geq 0$ such that:*

$$|J_\lambda^t z| \leq |z| + c'_1, \quad |\partial\varphi_\lambda^t(z)| \leq \lambda^{-1}(2|z| + c'_1)$$

for all $z \in H$, $t \in [0, T]$ and $\lambda \in (0, 1]$. (Here $J_\lambda^t = (I + \lambda\partial\varphi^t)^{-1}$).

- (iii) *$\varphi_\lambda^t(z) \geq (c_1/2)|z|^2 - \bar{c}_1$, for all $z \in H$, and all $0 < \lambda \leq 1/(2c_1)$.*
- (iv) *If $z_n \in D(\varphi^{t_n})$, $z_n \rightarrow z$ in H and $t_n \uparrow t$, as $n \rightarrow \infty$, then*

$$\varphi^t(z) \leq \liminf_{n \rightarrow \infty} \varphi^{t_n}(z_n).$$

- (v) *The functional $\Phi: \mathcal{H} \rightarrow [0, +\infty]$, defined by*

$$\Phi(v) = \int_0^T \varphi^t(v(t)) dt, \quad \forall v \in \mathcal{H}$$

is proper, convex, and l.s.c. Its regularization $\Phi_\lambda(\lambda > 0)$ is given by:

$$\Phi_\lambda(v) = \int_0^T \varphi_\lambda^t(v(t)) dt, \quad \forall v \in \mathcal{H}, \quad \lambda > 0.$$

In addition $(\partial\Phi_\lambda)(v)(t) = \partial\varphi_\lambda^t(v(t))$, a.e. on $(0, T)$, $\forall v \in \mathcal{H}$, and $v^ \in \partial\Phi(v)$ ($v, v^* \in \mathcal{H}$) iff $v^*(t) \in \partial\varphi^t(v(t))$, for a.a. $t \in (0, T)$.*

- (vi) *If $v \in W^{1,1}(0, T; H)$ and $\lambda > 0$, then $t \rightarrow \varphi_\lambda^t(v(t))$ is of bounded variation on $[0, T]$ and:*

$$(2.1) \quad \varphi_\lambda^t(v(t)) - \varphi_\lambda^s(v(s)) \leq \int_s^t \frac{d}{dr} \varphi_\lambda^r(v(r)) dr, \quad 0 \leq s \leq t \leq T.$$

In addition one has

$$\begin{aligned}
 (2.2) \quad & \frac{d}{dt} \varphi_\lambda^t(v(t)) - (v'(t)), \partial\varphi_\lambda^t(v(t)) \\
 & \leq |\alpha'(t)| |\partial\varphi_\lambda^t(v(t))| (1 + (\varphi_\lambda^t(v(t)))^{1/2}) \\
 & \quad + |\beta'(t)| (1 + \varphi_\lambda^t(v(t))), \text{ a.e. on } (0, T).
 \end{aligned}$$

3. Main result

We are primarily concerned with the existence of solutions to equation (1.1) under the key assumption that $A(t) = \partial\varphi^t$, $0 \leq t \leq T$, where $\varphi^t: H \rightarrow [0, +\infty]$ is proper, convex, and l.s.c. Besides (φ_1) and (φ_2) (see Section 2), the following condition will be used:

(φ_3) For each $t \in [0, T]$ and $r \geq 0$, the level set $\{z \in H: \varphi^t(z) \leq r\}$ is compact in H .

As regards the operator B in (1.1) we assume that:

- (b₁) $B = \partial j$, where $j: H \rightarrow]-\infty, +\infty]$ is proper, convex and l.s.c.
- (b₂) There exists $c_2 > 0$ such that

$$(y_2 - y_1, x_2 - x_1) \geq c_2 |x_2 - x_1|^2, \quad \forall y_i \in Bx_i, \quad i = 1, 2.$$

We now consider the Volterra integral equation (cf. (1.1))

$$(3.1) \quad u(t) + \int_0^t a(t-s) \partial\varphi^s(Bu(s)) ds \ni f(t), \quad 0 \leq t \leq T,$$

where φ^t and B satisfy conditions (φ_1) - (φ_3) , and (b_1) , (b_2) , respectively. The following restrictions on a and f will be imposed throughout:

- (a) $a \in W^{2,1}(0, T)$, $a(0) = 1$,
- (f) $f \in W^{2,1}(0, T; H)$, $f(0) \in D(B)$, $Bf(0) \cap D(\varphi^0) \neq \emptyset$.

Remark 3.1. The assumption $a(0) = 1$ in (a) is made only for simplicity. What we actually need is $a(0) > 0$. (Obviously, when $a(0) > 0$ one may replace a by $\tilde{a} = a(0)^{-1}a$ and φ^t by $a(0)\varphi^t$ to obtain $\tilde{a}(0) = 1$.)

Definition 3.2. A function $u: [0, T] \rightarrow H$ is called a solution to (3.1) if $u \in W^{1,2}(0, T; H)$, $u(t) \in D(B)$, a.e. on $(0, T)$, and there exist $v \in L^\infty(0, T; H)$, $w \in L^2(0, T; H)$ such that $v(t) \in Bu(t) \cap D(\partial\varphi^t)$, and $w(t) \in \partial\varphi^t(v(t))$, for a.a. $t \in (0, T)$, and $u(t) + a * w(t) = f(t)$ for all $t \in [0, T]$, where $*$ denotes the convolution $\left(a * w(t) = \int_0^t a(t-s) w(s) ds \right)$.

The main existence result is:

Theorem 3.3. *Let conditions (φ_1) - (φ_3) , (b_1) , (b_2) , (a) and (f) hold. Then equation (3.1) has at least one solution.*

Remark 3.4. (i) Theorem 3.3 extends (with no essential change in the proof) to equations of the form

$$u(t) + a*\partial\varphi^t(Bu(t)) + b*u(t) \ni f(t), \quad 0 \leq t \leq T,$$

where $b \in W^{1,1}(0, T)$.

- (ii) Since T in Theorem 3.3 is arbitrary, it is easy to formulate an existence result for equation (3.1) on $[0, +\infty]$. In such a case, it would be of interest to examine the asymptotic properties of solutions. We are going to address this question in a forthcoming paper.
- (iii) Theorem 3.3 can be regarded as a generalization of [20, Theorem 1.1].

We conclude this section with some remarks on the uniqueness of solutions of (3.1). As is well-known, nonuniqueness may occur even in the case when $a = 1$ (and (3.1) formally reduces to an equation of the type (1.4).) See [14, Section 5]. However, the uniqueness of solutions to (3.1) can easily be derived at the expense of additional restrictions on φ^t and B . A sample result is the following.

Theorem 3.5. *Let the conditions of Theorem 3.3 be satisfied. In addition assume that there exists $\eta \in L^1(0, T; \mathbf{R}_+)$ such that*

$$(3.2) \quad (z_2^t - z_1^t, x_2^t - x_1^t) \geq -\eta(t)|x_1^t - x_2^t|^2, \quad t \in [0, T],$$

for all $x_i^t \in D(B)$ with $Bx_i^t \cap D(\partial\varphi^t) \neq \emptyset$, and $z_i^t \in \partial\varphi^t(y_i^t)$, $y_i^t \in Bx_i^t$ ($i = 1, 2$). Then the solution u of equation (3.1) is uniquely determined.

Remark 3.6. Comparable uniqueness results for equation (1.2) may be found in [17].

4. Proofs

We first summarize some properties of B that are going to play an important role in the sequel.

Lemma 4.1 [20]. *Let (b_1) , (b_2) hold. Then*

- (i) B^{-1} is everywhere defined and Lipschitz continuous on H , and satisfies

$$(B^{-1}z_1 - B^{-1}z_2, z_1 - z_2) \geq c_2|B^{-1}z_1 - B^{-1}z_2|^2, \quad \forall z_1, z_2 \in H.$$

- (ii) $(B_\mu z_1 - B_\mu z_2, z_1 - z_2) \geq c_2(1 + \mu c_2)^{-1}|z_1 - z_2|^2$,

for all $z_1, z_2 \in H$ and $\mu > 0$.

(iii) $(B_\mu)^{-1}$ is everywhere defined on H , and

$$(B_\mu)^{-1}z = B^{-1}z + \mu z, \quad \forall z \in H, \mu > 0.$$

One of the key tools in the proof of our existence result is described next. Let (a) be satisfied, and define the resolvent kernel k of a' by:

$$(4.1) \quad k(t) + a' * k(t) = -a'(t), \quad t \in [0, T].$$

It is easily seen that $k \in W^{1,1}(0, T)$. Let $u \in W^{1,2}(0, T; H)$, $w \in L^2(0, T; H)$ and $f \in W^{1,2}(0, T; H)$ satisfy

$$(4.2) \quad u(t) + a * w(t) = f(t), \quad 0 \leq t \leq T.$$

Applying the method of [12, Proposition 1] we are led to

Lemma 4.2. *Let (a) hold, k be defined by (4.1), and $f \in W^{1,2}(0, T; H)$. Then $u \in W^{1,2}(0, T; H)$ and $w \in L^2(0, T; H)$ satisfy (4.2) if and only if*

$$(4.3) \quad \begin{aligned} (i) \quad & u'(t) + w(t) + k * u'(t) = F(t), \quad \text{a.e. on } (0, T), \\ (ii) \quad & u(0) = u_0, \end{aligned}$$

where

$$(4.4) \quad F(t) = f'(t) + k * f'(t), \quad u_0 = f(0).$$

Proof of Theorem 3.3. By assumption (f) and Lemma 4.1 (iii) we may define

$$(4.5) \quad u_{0,\mu} = (B_\mu)^{-1}u_0^*,$$

where $u_0 = f(0)$, and $u_0^* \in Bu_0 \cap D(\varphi^0)$. For each $\lambda, \mu > 0$, we consider the approximating equation

$$(4.6) \quad u_{\mu,\lambda}(t) + \int_0^t a(t-s) \partial \varphi_\lambda^2(B_\mu u_{\mu,\lambda}(s)) ds = f(t) + u_{0,\mu} - u_0, \quad 0 \leq t \leq T.$$

Inasmuch as $\partial \varphi_\lambda^t \circ B_\mu$ is Lipschitz continuous on H for each fixed t with Lipschitz constant independent of t (cf. Proposition 2.1 (ii)), and the mapping $t \rightarrow \partial \varphi_\lambda^t(B_\mu z)$ is measurable on $[0, T]$ for each fixed $z \in H$ (cf. Proposition 2.3 (i)), a usual contraction mapping argument shows that (4.6) has a unique solution $u_{\mu,\lambda} \in W^{1,2}(0, T; H)$.

Our aim is to obtain a number of a priori estimates involving $u_{\mu,\lambda}$, which will enable us to pass to the limit as $\lambda \downarrow 0$ in (4.6) (with μ fixed), and subsequently let $\mu \downarrow 0$. Instead of using (4.6) we apply Lemma 4.2 and consider the equivalent initial-value problem:

$$(4.7) \quad \begin{aligned} & \text{(i)} \quad u'_{\mu,\lambda}(t) + \partial\varphi_{\lambda}^t(B_{\mu}u_{\mu,\lambda}(t)) + k*u'_{\mu,\lambda}(t) = F(t), \quad \text{a.e. on } (0, T), \\ & \text{(ii)} \quad u_{\mu,\lambda}(0) = u_{0,\mu} \end{aligned}$$

where F is given by (4.4). Note that by (a), (f), (4.1), (4.4), one has $F \in W^{1,1}(0, T; H)$.

In what follows we will use c_3, c_4, \dots , etc. to denote various positive constants that are independent of μ and λ . We will also use inequalities of the following sort frequently and without comment:

$$(x + y)^{1/2} \leq x^{1/2} + y^{1/2}, \quad (x + y)^2 \leq 2(x^2 + y^2), \quad xy \leq (1/(2\varepsilon))x^2 + (\varepsilon/2)y^2,$$

for $x, y, \varepsilon \in (0, \infty)$. All estimates below are for $0 \leq t \leq T$, $0 < \lambda \leq \min\{1, 1/(2c_1)\}$, $0 < \mu \leq c_2^{-1}$.

First form the inner-product of (4.7) (i) with $(d/dt)B_{\mu}u_{\mu,\lambda}$ and integrate over $(0, t)$. Noting (see Lemma 4.1 (ii)) that

$$\left(\frac{d}{dt} B_{\mu}u_{\mu,\lambda}(t), u'_{\mu,\lambda}(t) \right) \geq c_2(1 + \mu c_2)^{-1} |u'_{\mu,\lambda}(t)|^2,$$

and using (2.1), (2.2), (4.5), (4.7) (ii), and the definition of φ_{λ}^0 (see Proposition 2.2), we obtain

$$(4.8) \quad \begin{aligned} & (c_2/2) \int_0^t |u'_{\mu,\lambda}(s)|^2 ds + \varphi_{\lambda}^t(B_{\mu}u_{\mu,\lambda}(t)) \\ & \quad + \int_0^t \left(k*u'_{\mu,\lambda}(s), \frac{d}{ds} B_{\mu}u_{\mu,\lambda}(s) \right) ds \\ & \leq \varphi^0(u_0^*) + \int_0^t \left(F(s), \frac{d}{ds} B_{\mu}u_{\mu,\lambda}(s) \right) ds \\ & \quad + \int_0^t |\alpha'(s)| |\partial\varphi_{\lambda}^s(B_{\mu}u_{\mu,\lambda}(s))| (1 + [\varphi_{\lambda}^s(B_{\mu}u_{\mu,\lambda}(s))]^{1/2}) ds \\ & \quad + \int_0^t |\beta'(s)| (1 + \varphi_{\lambda}^s(B_{\mu}u_{\mu,\lambda}(s))) ds. \end{aligned}$$

Remark that

$$(4.9) \quad \begin{aligned} & \int_0^t \left(k*u'_{\mu,\lambda}(s), \frac{d}{ds} B_{\mu}u_{\mu,\lambda}(s) \right) ds = (k*u'_{\mu,\lambda}(t), B_{\mu}u_{\mu,\lambda}(t)) \\ & \quad - \int_0^t (B_{\mu}u_{\mu,\lambda}(s), k(0)u'_{\mu,\lambda}(s) + k'*u'_{\mu,\lambda}(s)) ds, \end{aligned}$$

while (cf. (4.4), (4.5))

$$(4.10) \quad \int_0^t \left(F(s), \frac{d}{ds} B_\mu u_{\mu,\lambda}(s) \right) ds = (F(t), B_\mu u_{\mu,\lambda}(t)) - (f'(0), u_0^*) - \int_0^t (F'(s), B_\mu u_{\mu,\lambda}(s)) ds.$$

Setting

$$(4.11) \quad X_{\mu,\lambda}(t) = \varphi_\lambda^t(B_\mu u_{\mu,\lambda}(t)) - (B_\mu u_{\mu,\lambda}(t), F(t))$$

and using (4.9), (4.10) in (4.8) yields

$$(4.12) \quad \begin{aligned} (c_2/2) \int_0^t |u'_{\mu,\lambda}(s)|^2 ds + X_{\mu,\lambda}(t) &\leq c_3 + |k * u'_{\mu,\lambda}(t)| |B_\mu u_{\mu,\lambda}(t)| \\ &+ \int_0^t (B_\mu u_{\mu,\lambda}(s), k(0)u'_{\mu,\lambda}(s) + k' * u'_{\mu,\lambda}(s)) ds - \int_0^t (F'(s), B_\mu u_{\mu,\lambda}(s)) ds \\ &+ \int_0^t |\alpha'(s)| |\partial \varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))| (1 + [\varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))]^{1/2}) ds \\ &+ \int_0^t |\beta'(s)| (1 + \varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))) ds. \end{aligned}$$

Next observe that (4.11) and (iii) of Proposition 2.3 imply

$$(4.13) \quad (c_1/2) |B_\mu u_{\mu,\lambda}(t)|^2 - \bar{c}_1 \leq \varphi_\lambda^t(B_\mu u_{\mu,\lambda}(t)) \leq c_4 X_{\mu,\lambda}(t) + c_5 |F(t)|^2 + c_6.$$

We now seek to bound the right-hand side of (4.12), in terms of $X_{\mu,\lambda}(t)$ and

$\int_0^t |u'_{\mu,\lambda}(s)| ds$. We first have

$$(4.14) \quad \begin{aligned} |k * u'_{\mu,\lambda}(t)| |B_\mu u_{\mu,\lambda}(t)| &\leq \max_{[0,T]} |k| \left(\int_0^t |u'_{\mu,\lambda}(s)| ds \right) |B_\mu u_{\mu,\lambda}(t)| \\ &\leq c_7 \left[\int_0^t |u'_{\mu,\lambda}(s)| ds \right]^2 + c_8 |B_\mu u_{\mu,\lambda}(t)|^2, \end{aligned}$$

where c_8 is to be sufficiently small, in a sense to be precised later. Invoking (4.13) in (4.14) implies

$$(4.15) \quad |k * u'_{\mu,\lambda}(t)| |B_\mu u_{\mu,\lambda}(t)| \leq c_9 \left[\int_0^t |u'_{\mu,\lambda}(s)| ds \right]^2 + c_{10} X_{\mu,\lambda}(t) + c_{11},$$

with a sufficiently small c_{10} .

In the following, we will continue to make use of (4.13) repeatedly, and without comment. We have

$$\begin{aligned}
 (4.16) \quad k(0) \int_0^t (B_\mu u_{\mu,\lambda}(s), u'_{\mu,\lambda}(s)) ds &\leq |k(0)| \int_0^t |B_\mu u_{\mu,\lambda}(s)| |u'_{\mu,\lambda}(s)| ds \\
 &\leq c_{12} \int_0^t |u'_{\mu,\lambda}(s)|^2 ds + c_{13} \int_0^t X_{\mu,\lambda}(s) ds + c_{14},
 \end{aligned}$$

where c_{12} is small enough. Similarly,

$$\begin{aligned}
 (4.17) \quad \int_0^t (B_\mu u_{\mu,\lambda}(s), k' * u'_{\mu,\lambda}(s)) ds &\leq \|k'\|_{L^1(0,T)} \|B_\mu u_{\mu,\lambda}\|_{L^2(0,t;H)} \|u'_{\mu,\lambda}\|_{L^2(0,t;H)} \\
 &\leq c_{15} \int_0^t |u'_{\mu,\lambda}(s)|^2 ds + c_{16} \int_0^t X_{\mu,\lambda}(s) ds + c_{17},
 \end{aligned}$$

with a sufficiently small c_{15} .

We now consider $\int_0^t (F'(s), B_\mu u_{\mu,\lambda}(s)) ds$. By (a), (f) and (4.4), it follows that $F' \in L^1(0, T; H)$. Also note that (4.13) implies $|B_\mu u_{\mu,\lambda}(t)| \leq c_{18} + (1/2)X_{\mu,\lambda}(t)$. We consequently deduce that:

$$\begin{aligned}
 (4.18) \quad - \int_0^t (F'(s), B_\mu u_{\mu,\lambda}(s)) ds &\leq \int_0^t (c_{18} + (1/2)X_{\mu,\lambda}(s)) |F'(s)| ds \\
 &\leq c_{19} + \int_0^t \theta_1(s) X_{\mu,\lambda}(s) ds,
 \end{aligned}$$

where $\theta_1(t) = (1/2)|F'(t)|$, $\theta_1 \in L^1(0, T)$.

We next see that

$$(4.19) \quad \int_0^t |\beta'(s)| (1 + \varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))) ds \leq c_{20} + \int_0^t \theta_2(s) X_{\mu,\lambda}(s) ds,$$

where $\theta_2(t) = \text{const} |\beta'(t)|$, $\theta_2 \in L^1(0, T)$ (cf. (φ_2)).

It remains to estimate

$$\int_0^t |\alpha'(s)| |\partial \varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))| (1 + [\varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))]^{1/2}) ds.$$

By (4.7) (i) one has

$$|\partial \varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))| \leq |F(s)| + |u'_{\mu,\lambda}(s)| + |k * u'_{\mu,\lambda}(s)|, \quad 0 \leq s \leq t.$$

We successively obtain

$$(4.20) \quad \int_0^t |\alpha'(s)| |F(s)| (1 + [\varphi_\lambda^s(B_\mu u_{\mu,\lambda}(s))]^{1/2}) ds$$

$$\begin{aligned} &\leq c_{21} + \max_{[0, T]} |F| \|\alpha'\|_{L^2(0, T)} \left[\int_0^t \varphi_\lambda^s(B_\mu u_{\mu, \lambda}(s)) ds \right]^{1/2} \\ &\leq c_{22} + c_{23} \int_0^t X_{\mu, \lambda}(s) ds, \end{aligned}$$

and

$$\begin{aligned} (4.21) \quad &\int_0^t |\alpha'(s)| |u'_{\mu, \lambda}(s)| (1 + [\varphi_\lambda^s(B_\mu u_{\mu, \lambda}(s))]^{1/2}) ds \\ &\leq c_{24} \int_0^t |u'_{\mu, \lambda}(s)|^2 ds + \int_0^t \theta_3(s) X_{\mu, \lambda}(s) ds + c_{25}, \end{aligned}$$

where c_{24} is small enough and $\theta_3(t) = \text{const} |\alpha'(t)|^2$, $\theta_3 \in L^1(0, T)$ (cf. (φ_2)). We finally have

$$\begin{aligned} (4.22) \quad &\int_0^t |\alpha'(s)| |k * u'_{\mu, \lambda}(s)| (1 + [\varphi_\lambda^s(B_\mu u_{\mu, \lambda}(s))]^{1/2}) ds \\ &\leq c_{26} \int_0^t |\alpha'(s)|^2 ds + c_{27} \int_0^t |k * u'_{\mu, \lambda}(s)|^2 ds \\ &\quad + c_{28} \int_0^t |\alpha'(s)|^2 \varphi_\lambda^s(B_\mu u_{\mu, \lambda}(s)) ds \\ &\leq c_{29} \int_0^t |u'_{\mu, \lambda}(s)|^2 ds + \int_0^t \theta_4(s) X_{\mu, \lambda}(s) ds + c_{30}, \end{aligned}$$

where c_{29} is sufficiently small and $\theta_4(t) = \text{const} |\alpha'(t)|^2$, $\theta_4 \in L^1(0, T)$.

By combining (4.12), and (4.15)–(4.22), we get

$$\begin{aligned} (4.23) \quad &(c_2/2) \int_0^t |u'_{\mu, \lambda}(s)|^2 ds + X_{\mu, \lambda}(t) \leq c_{31} + c_9 \left[\int_0^t |u'_{\mu, \lambda}(s)| ds \right]^2 \\ &\quad + c_{10} X_{\mu, \lambda}(t) + c_{32} \int_0^t |u'_{\mu, \lambda}(s)|^2 ds + \int_0^t \theta(s) X_{\mu, \lambda}(s) ds, \end{aligned}$$

where

$$\begin{aligned} c_{32} &= c_{12} + c_{15} + c_{24} + c_{29}, \\ \theta(t) &= c_{13} + c_{16} + c_{23} + \sum_{i=1}^4 \theta_i(t); \theta \in L^1(0, T; \mathbf{R}_+). \end{aligned}$$

It is now clear that c_{12} , c_{15} , c_{24} , c_{29} and c_{10} can be chosen so small that

$$(4.24) \quad c_{32} < c_2/2, \quad c_{10} < 1.$$

Employing (4.24) in (4.23) yields

$$(4.25) \quad \begin{aligned} & c_{33} \int_0^t |u'_{\mu,\lambda}(s)|^2 ds + c_{34} X_{\mu,\lambda}(t) \\ & \leq c_{31} + c_9 \left[\int_0^t |u'_{\mu,\lambda}(s)| ds \right]^2 + \int_0^t \theta(s) X_{\mu,\lambda}(s) ds. \end{aligned}$$

For fixed t , and $0 \leq s \leq t$, (4.25) implies

$$(4.26) \quad c_{34} X_{\mu,\lambda}(s) \leq c_{31} + c_9 \left[\int_0^t |u'_{\mu,\lambda}(\tau)| d\tau \right]^2 + \int_0^s \theta(\tau) X_{\mu,\lambda}(\tau) d\tau,$$

Applying Gronwall's inequality to (4.26) we infer that

$$(4.27) \quad X_{\mu,\lambda}(t) \leq c_{35} \left[1 + \left[\int_0^t |u'_{\mu,\lambda}(\tau)| d\tau \right]^2 \right], \quad 0 \leq t \leq T.$$

From (4.25) and (4.27) it follows that

$$(4.28) \quad \int_0^t |u'_{\mu,\lambda}(s)|^2 ds \leq c_{36} \left[1 + \left[\int_0^t |u'_{\mu,\lambda}(s)| ds \right]^2 \right].$$

This inequality is completely similar to (2.29) in [13, p. 714]. Arguing as in [13], we see that (4.28) leads to

$$(4.29) \quad \|u'_{\mu,\lambda}\| \leq c_{38},$$

(where $\|\cdot\|$ denotes the \mathcal{H} -norm; $\mathcal{H} = L^2(0, T; H)$).

Together, (4.27) and (4.29) imply

$$(4.30) \quad X_{\mu,\lambda}(t) \leq c_{38}.$$

Finally, from (4.13) and (4.30) we get

$$(4.31) \quad |B_\mu u_{\mu,\lambda}(t)| + \varphi_\lambda^t(B_\mu u_{\mu,\lambda}(t)) \leq c_{39}.$$

On account of (4.29)–(4.31) we can now pass to the limit in (4.7) as $\lambda \downarrow 0$ (with μ fixed) and then let $\mu \downarrow 0$. Since the procedure follows that of [20, pp. 1195–96], we only sketch it.

Using the compactness assumption (φ_3) , Proposition 2.1 (ii), Proposition 2.2 (i), (ii), and Lemma 4.1 (ii), in conjunction with (4.29)–(4.31), we conclude that there exist a sequence $\lambda_n \downarrow 0$ (as $n \rightarrow \infty$), and a function $u_\mu \in W^{1,2}(0, T; H)$ such that

$$(4.32) \quad \begin{array}{lll} \text{(i)} & u_{\mu,\lambda_n} \longrightarrow u_\mu, & \text{in } C([0, T]; H), \\ \text{(ii)} & u'_{\mu,\lambda_n} \longrightarrow u'_\mu, & \text{in } \mathcal{H}, \end{array}$$

$$(iii) \quad B_\mu u_{\mu, \lambda_n} \longrightarrow B_\mu u_\mu, \quad \text{in } C([0, T]; H).$$

In addition, one has

$$(4.33) \quad |u_\mu(t)| + \|u'_\mu\| + \varphi'(B_\mu u_\mu(t)) \leq c_{40}, \quad 0 \leq t \leq T,$$

where c_{40} is independent of μ .

Invoking (4.32) (ii) in (4.7) (i) implies

$$(4.34) \quad \partial\varphi_{\lambda_n}^t(B_\mu u_{\mu, \lambda_n}(t)) \longrightarrow F(t) - u'_\mu(t) - k*u'_\mu(t), \quad \text{in } \mathcal{H}.$$

In view of Proposition (2.1) (iii) and Proposition (2.3) (v), it follows from (4.32) (iii) and (4.34) that

$$(4.35) \quad F(t) - u'_\mu(t) - k*u'_\mu(t) \in \partial\varphi'(B_\mu u_\mu(t)), \quad \text{a.e. on } (0, T).$$

Writing (4.7) with $\lambda = \lambda_n$ and letting $\lambda_n \downarrow 0$ now yields, by (4.32) (ii), (4.35)

$$(4.36) \quad \begin{aligned} (i) \quad & u'_\mu(t) + \partial\varphi'(B_\mu u_\mu(t)) + k*u'_\mu(t) \ni F(t), \quad \text{a.e. on } (0, T), \\ (ii) \quad & u_\mu(0) = u_{0, \mu}, \end{aligned}$$

where u_μ satisfies (4.33).

It remains to let $\mu \downarrow 0$ in (4.36). By virtue of (4.33), (φ_3) , Proposition 2.1 and Lemma 4.1, we can again find a sequence $\mu_n \downarrow 0$ (as $n \rightarrow \infty$) such that

$$(4.37) \quad \begin{aligned} (i) \quad & u_{\mu_n} \longrightarrow u, \quad \text{in } C([0, T]; H), \\ (ii) \quad & u'_{\mu_n} \longrightarrow u', \quad \text{in } \mathcal{H}, \\ (iii) \quad & B_{\mu_n} u_{\mu_n} \longrightarrow v, \quad \text{weakly in } \mathcal{H} \text{ and weakly-star in } L^\infty(0, T; H), \end{aligned}$$

where $u \in W^{1,2}(0, T; H)$, $v \in L^\infty(0, T; H)$ and $v(t) \in Bu(t)$, a.e. on $(0, T)$. In particular, (4.36) (ii), (4.37) (i), and Lemma 4.1 (iii) yield

$$(4.38) \quad u(0) = u_0.$$

Also, (4.37) (ii) leads to

$$(4.39) \quad F(t) - k*u'_{\mu_n}(t) - u'_{\mu_n}(t) \longrightarrow w, \quad \text{in } \mathcal{H},$$

where $w(t) = F(t) - u'(t) - k*u'(t)$, a.e. $t \in (0, T)$. Calling on (4.36) (i), (4.37) (iii) and (4.39), we see that we only need to show that (cf. Proposition 2.3 (v))

$$(4.40) \quad w \in \partial\Phi(v).$$

Let $q \in \mathcal{H}$ with $\varphi'(q(t)) \in L^1(0, T)$, i.e., $q \in D(\Phi)$ (cf. Proposition (2.3) (v)). By (4.35), (4.36) (i), (4.37) (iii) and (4.39) it is easily verified that

$$(4.41) \quad \Phi(q) - \Phi(v) \geq \lim_{n \rightarrow \infty} \langle F - u'_{\mu_n} - k*u'_{\mu_n}, q - B_{\mu_n} u_{\mu_n} \rangle,$$

where $\langle \cdot, \cdot \rangle$ denotes the inner product in \mathcal{H} . Employing (b₁), Proposition (2.2) (ii), (iii), and (4.37) we deduce that

$$\lim_{n \rightarrow \infty} \langle u'_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle = j(u(T)) - j(u(0)) = \langle u', v \rangle,$$

and consequently

$$(4.42) \quad \lim_{n \rightarrow \infty} \langle F - u'_{\mu_n}, q - B_{\mu_n} u_{\mu_n} \rangle = \langle F - u', q - v \rangle.$$

Let us now check that

$$(4.43) \quad \lim_{n \rightarrow \infty} \langle k * u'_{\mu_n}, q - B_{\mu_n} u_{\mu_n} \rangle = \langle k * u', q - v \rangle.$$

Since it is obvious that $\langle k * u'_{\mu_n}, q \rangle \rightarrow \langle k * u', q \rangle$, as $n \rightarrow \infty$, we only have to prove (cf. (4.43))

$$(4.44) \quad \lim_{n \rightarrow \infty} \langle k * u'_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle = \langle k * u', v \rangle.$$

Remarking that ($k \in W^{1,1}(0, T)$)

$$k * u'_{\mu_n}(t) = k(t)u_{0, \mu_n} - k(0)u_{\mu_n}(t) + k' * u_{\mu_n}(t),$$

we obtain

$$(4.45) \quad \langle k * u'_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle = \langle k(\cdot)u_{0, \mu_n}, B_{\mu_n} u_{\mu_n} \rangle - k(0)\langle u_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle + \langle k' * u_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle.$$

Clearly $k(t)u_{0, \mu_n} \rightarrow k(t)u(0)$, strongly in \mathcal{H} . This in conjunction with (4.37) (iii) and (4.38) implies

$$(4.46) \quad \lim_{n \rightarrow \infty} \langle k(\cdot)u_{0, \mu_n}, B_{\mu_n} u_{\mu_n} \rangle = \langle k(\cdot)u(0), v \rangle.$$

By (4.37) (i), (iii) we also have

$$(4.47) \quad k(0)\langle u_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle \longrightarrow k(0)\langle u, v \rangle \quad (n \longrightarrow \infty).$$

Inasmuch as $k' * u_{\mu_n} \rightarrow k' * u$, strongly in \mathcal{H} , we finally infer that

$$(4.48) \quad \langle k' * u_{\mu_n}, B_{\mu_n} u_{\mu_n} \rangle \longrightarrow \langle k' * u, v \rangle \quad (n \longrightarrow \infty).$$

On account of (4.45)–(4.48) we now arrive at (4.44). It follows that (4.43) also holds. Using (4.42), (4.43) in (4.41) yields

$$\Phi(q) - \Phi(v) \geq \langle w, q - v \rangle,$$

which, according to the definition of a subdifferential, is equivalent to (4.40).

The passage to the limit in (4.7) (equivalently, (4.6)) is now completed. We conclude that the functions $u \in W^{1,2}(0, T; H)$, $v \in L^\infty(0, T; H)$ with $v(t) \in Bu(t)$, a.e., and $w \in L^2(0, T; H)$, with $w(t) \in \partial\phi'(v(t))$, a.e., satisfy (4.3). By Lemma 4.2 this means that u is a solution of (3.1) in the sense of Definition 3.2. The proof is closed.

Proof of Theorem 3.5. Let u_1 and u_2 be two solutions of (3.1) (cf. Definition 3.2), and $p(t) = u_1(t) - u_2(t)$, $0 \leq t \leq T$. Invoking Lemma 4.2, it is easily seen that

$$(4.49) \quad \begin{aligned} (i) \quad & p'(t) + w_1(t) - w_2(t) + k * p'(t) = 0, \quad \text{a.e. } t \in (0, T), \\ (ii) \quad & p(0) = 0, \end{aligned}$$

where $w_i(t) \in \partial\phi'(v_i(t))$, $v_i(t) \in Bu_i(t)$, a.e. on $(0, T)$, $i = 1, 2$. Multiplying (4.49) (i) by $p(t)$ and making use of condition (3.2) leads to:

$$(1/2) \frac{d}{dt} |p(t)|^2 \leq \eta(t) |p(t)|^2 - (k(0)p(t) + k' * p(t), p(t)).$$

This implies

$$(4.50) \quad (1/2) \frac{d}{dt} |p(t)|^2 \leq (\eta(t) + |k(0)|) |p(t)|^2 + (|k'| * |p|(t)) |p(t)|.$$

Integrate (4.50) over $(0, t)$ and use (4.49) (ii) to find

$$|p(t)|^2 \leq 2 \int_0^t (\eta(s) + |k(0)|) |p(s)|^2 ds + \|k'\|_{L^1(0, T)} \int_0^t |p(s)|^2 ds,$$

or equivalently

$$(4.51) \quad |p(t)|^2 \leq \int_0^t \eta_1(s) |p(s)|^2 ds, \quad 0 \leq t \leq T,$$

where $\eta_1(t) = 2(\eta(t) + |k(0)|) + \|k'\|_{L^1(0, T)}$, $\eta_1 \in L^1(0, T; \mathbf{R}_+)$. An application of Gronwall's inequality to (4.51) yields $p \equiv 0$, i.e., $u_1 \equiv u_2$, and the proof is complete.

5. An example

In this section we suggest a special heat flow model to which our previous theory applies. This can be regarded as a generalization of the discussion in [2, Section 5] and [15, Section 4]. See also [7, Section 4].

Consider a homogenous bar of unit length of a material with memory,

and let $u(t, x)$, $e(t, x)$, $q(t, x)$ and $r(t, x)$ denote respectively the temperature, internal energy, heat flux, and external heat supply at time t and position x ($0 \leq t \leq T$, $0 \leq x \leq 1$). For simplicity let the history of u be prescribed as zero for $t < 0$, $0 \leq x \leq 1$. We assume that e and q are given by:

$$(5.1) \quad \begin{aligned} e(t, x) &= b_0 g(u(t, x)) + \int_0^t \delta(t-s) g(u(s, x)) ds, \\ q(t, x) &= -a_0 u_x(t, x) + \int_0^t \gamma(t-s) u_x(s, x) ds, \end{aligned}$$

where $0 \leq t \leq T$, $0 \leq x \leq 1$, $a_0 > 0$, $b_0 > 0$, while $\delta, \gamma: \mathbf{R}_+ \rightarrow \mathbf{R}$ and $g: \mathbf{R} \rightarrow \mathbf{R}$ are sufficiently smooth functions. The energy balance equation takes the form $e_t = -q_x + r$. If also $u(0, x) = u_0(x)$ ($0 \leq x \leq 1$) is the initial temperature distribution, then (5.1) leads to:

$$(5.2) \quad \begin{aligned} (i) \quad & \frac{d}{dt} [b_0 g(u) + \delta * g(u)] = a_0 u_{xx} - \gamma * u_{xx} + r, \\ (ii) \quad & u(0, x) = u_0(x), \end{aligned}$$

where $0 \leq t \leq T$, $0 \leq x \leq 1$.

To (5.2) we add the following boundary conditions at $x = 0$ and $x = 1$, expressing the presence of thermostatic controls at the ends of the rod:

$$(5.3) \quad \begin{aligned} m_0(t) \leq u(t, 0) \leq n_0(t) & \quad (0 \leq t \leq T) \\ u_x(t, 0^+) \leq g_0(m_0(t)) & \quad \text{if } u(t, 0) = m_0(t) \\ u_x(t, 0^+) = g_0(u(t, 0)) & \quad \text{if } m_0(t) < u(t, 0) < n_0(t) \\ u_x(t, 0^+) \geq g_0(n_0(t)) & \quad \text{if } u(t, 0) = n_0(t) \end{aligned}$$

and

$$(5.4) \quad \begin{aligned} m_1(t) \leq u(t, 1) \leq n_1(t) & \quad (0 \leq t \leq T) \\ -u_x(t, 1^-) \leq g_1(m_1(t)) & \quad \text{if } u(t, 1) = m_1(t) \\ -u_x(t, 1^-) = g_1(u(t, 1)) & \quad \text{if } m_1(t) < u(t, 1) < n_1(t) \\ -u_x(t, 1^-) \geq g_1(n_1(t)) & \quad \text{if } u(t, 1) = n_1(t) \end{aligned}$$

Here m_i, n_i ($i = 0, 1$) are real functions on $[0, T]$ such that

$$(5.5) \quad \begin{aligned} m_i, n_i \in W^{1,2}(0, T); m_i < n_i & \quad \text{on } [0, T], \\ 0 \in [m_i(0), n_i(0)], & \end{aligned}$$

while $g_i: \mathbf{R} \rightarrow \mathbf{R}$ ($i = 0, 1$) satisfies

(5.6) g_i is continuous and nondecreasing on \mathbf{R} , with $g_i(0) = 0$.

Next let $\sigma: [0, T] \rightarrow \mathbf{R}$ be the solution of $b_0(\sigma(t) + (\delta * \sigma)(t)) = -\delta(t)/b_0$, and define

$$(5.7) \quad a(t) = (K(t)/b_0) + \sigma * K(t), \quad K(t) = a_0 - \int_0^t \gamma(s) ds,$$

$$(5.8) \quad f(t, \cdot) = (\Gamma(t, \cdot)/b_0) + \sigma * \Gamma(t, \cdot),$$

$$\Gamma(t, x) = b_0 g(u_0(x)) + \int_0^t r(s, x) ds.$$

Then (5.2)–(5.4) is formally equivalent to

$$(5.9) \quad g(u) - a * u_{xx} = f \quad (0 \leq t \leq T, 0 \leq x \leq 1),$$

where u satisfies (5.3), (5.4) and a, f are given by (5.7), (5.8) respectively. This can further be rewritten as a Volterra equation of the form (3.1) in the Hilbert space $H = L^2(0, 1)$. As in [2], let $G_i(t) = \int_0^t g_i(s) ds$ ($0 \leq t \leq T$), $i = 0, 1$, and introduce the proper convex, l.s.c. functional $\varphi^t: H \rightarrow [0, +\infty]$ by

$$(5.10) \quad \varphi^t(z) = \begin{cases} (1/2)|z_x|_H^2 + G_0(z(0)) + G_1(z(1)), & \text{if } z \in \Delta(t), \\ +\infty & \text{otherwise} \end{cases}$$

where

$$\Delta(t) = \{z \in W^{1,2}(0, 1): m_0(t) \leq z(0) \leq n_0(t), m_1(t) \leq z(1) \leq n_1(t)\}.$$

In view of (5.5), (5.6) it is easily seen that the functions φ^t given by (5.10) for all $t \in [0, T]$ satisfy (φ_1) and (φ_3) . Moreover, by [15, Lemma 2], condition (φ_2) also holds. Finally, invoking Lemma 5 in [15], we conclude that $\partial\varphi^t(z) = -z_{xx}$, in the distributional sense on $(0, 1)$, where $D(\partial\varphi^t)$ consists of all $z \in W^{2,2}(0, 1)$ satisfying (5.3), (5.4) with $z(0), z_x(0^+)$, and $z(1), z_x(1^-)$ in place of $u(t, 0), u_x(t, 0^+)$, and $u(t, 1), u_x(t, 1^-)$, respectively. The above remarks show that (5.9) together with the boundary conditions (5.3), (5.4) reduces to the following integral equation in H :

$$(5.11) \quad \tilde{g}(u(t)) + \int_0^t a(t-s)\partial\varphi^s(u(s))ds \ni \tilde{f}(t), \quad t \in [0, T],$$

where $\tilde{g}(z)(x) = g(z(x))$, a.e. $x \in (0, 1)$, $\forall z \in H$, and $\tilde{f}(t)(x) = f(t, x)$ ($t \in [0, T], x \in (0, 1)$), provided that appropriate restrictions are imposed on g and f . Equation (5.11) is essentially of the form (1.2) and can be rewritten as (3.1) with $B = \tilde{g}^{-1}$.

Our aim is to apply now Theorem 3.3 to obtain an existence result for (5.11). We only need to make some technical assumptions on δ , γ , r , u_0 and g to ensure that (a), (f), (b₁) and (b₂) are satisfied. Specifically, we assume

$$(5.12) \quad \delta \in W^{2,1}(0, T), \quad \gamma \in W^{1,1}(0, T),$$

$$(5.13) \quad r \in W^{1,1}(0, T; L^2(0, 1)),$$

$$(5.14) \quad u_0 \in W_0^{1,2}(0, 1),$$

$$(5.15) \quad g: \mathbf{R} \longrightarrow \mathbf{R} \text{ is continuous, nondecreasing, } g(0) = 0 \text{ and}$$

$$(g(x_2) - g(x_1))(x_2 - x_1) \geq c |g(x_2) - g(x_1)|^2, \quad \forall x_1, x_2 \in \mathbf{R},$$

for some $c > 0$.

If $B = \tilde{g}^{-1}$ and a, f, φ' are defined by (5.7), (5.8) and (5.10), respectively, it is easily verified that conditions (5.12)–(5.15) in conjunction with (5.5), (5.6) imply (a), (f), (b₁) and (b₂). Note that although $a(0) = a_0/b_0$, which may be different from 1, this case can be reduced to $a(0) = 1$; see Remark 3.1.

The following is a direct consequence of Theorem 3.3.

Theorem 5.1. *Let (5.5), (5.6), (5.12)–(5.15) be satisfied. Then the Volterra equation (5.11) (or equivalently the heat flow problem (5.2)–(5.4)) has at least one solution $u \in L^\infty(0, T; L^2(0, 1))$, such that $g(u) \in W^{1,2}(0, T; L^2(0, 1))$, $u(t, \cdot) \in W^{2,2}(0, 1)$, a.e. on $(0, T)$, and $u_{xx} \in L^2(0, T; L^2(0, 1))$.*

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(Ricevita la 2-an de septembro, 1991)

(Reviziita la 4-an de aprilo, 1992)